

$$y' = ty + \frac{t^3}{y} =: f(t, y)$$

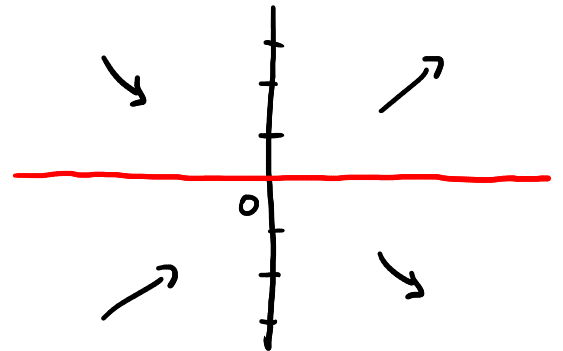
$$\text{dom}(f) = \mathbb{R} \times \mathbb{R}^*$$

$$f \in C^1 \Rightarrow \text{TEUL} \checkmark$$

TEUG  $\times$  (dominio non di "tipo striscia")

$$f(t, y) = ty \left( 1 + \frac{t^2}{y^2} \right)$$

$> 0$



$$f(t, y) = 0 \Leftrightarrow t = 0 \quad \text{zero-clina}$$

$$f(t, y) > 0 \Leftrightarrow ty > 0$$

Asintoti?  $y' = ty + \frac{t^3}{y}$

diverge  
per  $t \rightarrow +\infty$   
se  $y(t) \rightarrow \alpha \in \mathbb{R}$

$\Rightarrow$  eventuali soluz. definite

in intervalli illimitati superiormente (o inferiormente)

divergono

$$y' = ty + \frac{t^3}{y}$$

$$yy' = ty^2 + t^3$$

$$z = y^2 \quad z > 0$$

$$2yy' = 2ty^2 + 2t^3$$

$$z' = 2yy'$$

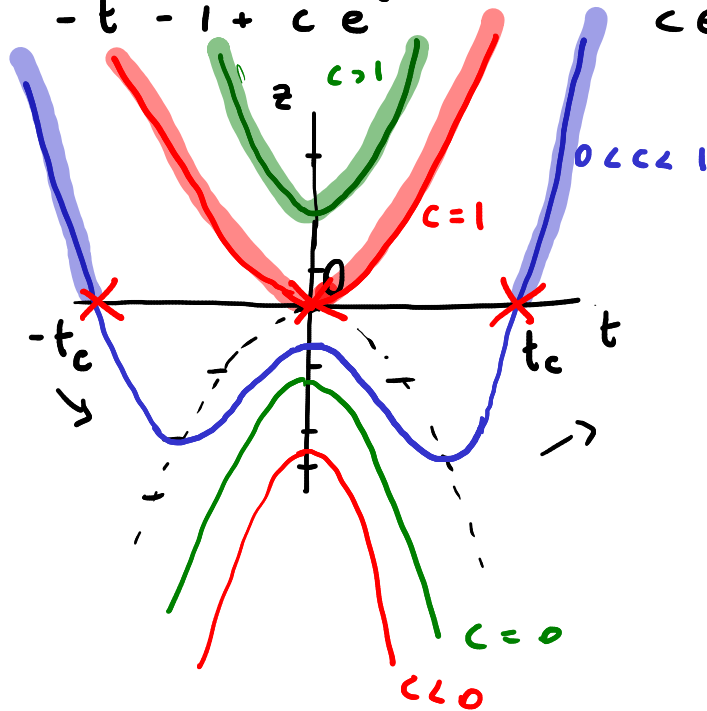
$$z' = 2tz + 2t^3 = 2t(z + t^2)$$

$$z(t) = e^{t^2} \int e^{-t^2} (2t^3) dt$$

$$\int e^{-t^2} (2t^3) dt = \int \underbrace{(-2t)}_{\text{derivative of } e^{-t^2}} e^{-t^2} (-t^2) dt$$

$$\begin{aligned}
 &= e^{-t^2} (-t^2) - \int e^{-t^2} (-2t) dt \\
 &= -t^2 e^{-t^2} - e^{-t^2} + c \quad c \in \mathbb{R}
 \end{aligned}$$

$$\Rightarrow z_c(t) = -t^2 - 1 + c e^{t^2} \quad c \in \mathbb{R}$$



$c > 0$ :

$$z_c(t) \rightarrow +\infty \quad t \rightarrow \pm\infty$$

$$z_c(0) = 0$$

$$-1 + c = 0 \quad c = 1$$

$$z = y^2 \Rightarrow y = \pm\sqrt{z} \quad (\text{dove } \bar{e} \text{ lecito})$$

$$c > 1: \varphi_c^\pm(t) = \pm\sqrt{z_c(t)} \quad t \in \mathbb{R}$$

$$c = 1 \quad \varphi_1^\pm(t) = \pm\sqrt{z_1(t)} \quad t \in ]0, +\infty[$$

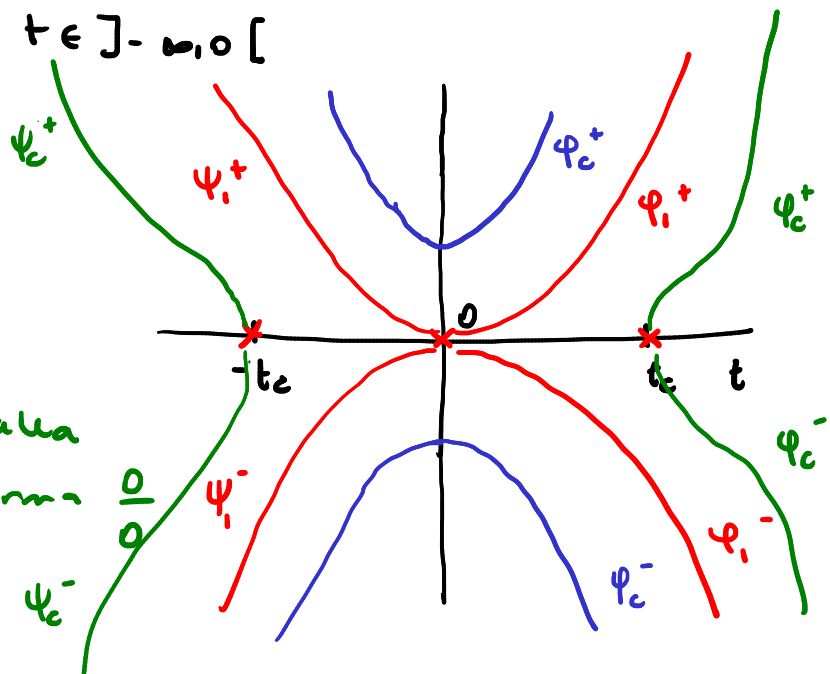
$$\varphi_1^\pm(t) = \pm\sqrt{z_1(t)} \quad t \in ]-\infty, 0[$$

$$\varphi_1^\pm(t) \rightarrow 0 \quad t \rightarrow 0$$

Con quale pendenza?

Non posso deciderlo dalla eq. diff., che presenta forma

$$z_1(t) = -t^2 - 1 + e^{t^2}$$



per  $t \rightarrow 0 \rightarrow = -\cancel{t^2} - 1 + \cancel{1} + \cancel{t^2} + \frac{t^4}{2} + o(t^2)$

$\Rightarrow$  per  $t \rightarrow 0$ :  $\varphi_c(t) \sim \frac{t^2}{\sqrt{2}}$

$0 < c < 1$ :  $\varphi_c^+(t) = \pm \sqrt{2c}t$   $t \in ]t_c, +\infty[$

$\varphi_c^-(t) = \pm \sqrt{2c}t$   $t \in ]-\infty, t_c[$

per  $t \rightarrow t_c^+$ :  $\varphi_c^+(t) \rightarrow 0$

Dalle equaz. diff:

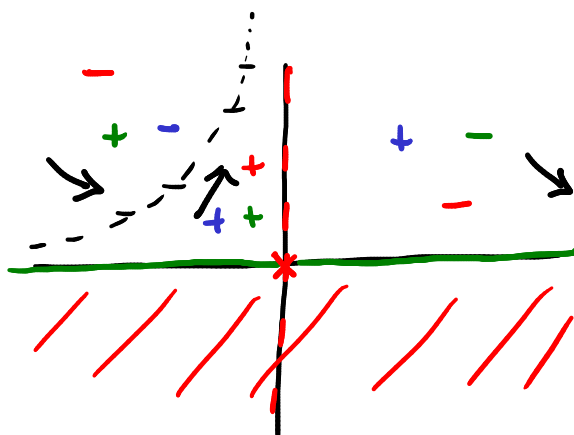
$\varphi_c^+(t) = t \varphi_c^+(t) + \frac{t^3}{\varphi_c^+(t)} \rightarrow +\infty$   
 $t_c > 0$   
 $\downarrow \quad \downarrow$   
 $t_c \quad 0$   
 $\downarrow$   
 $0$

$y' = -\frac{6}{t}y - 2t^2 y^{3/2} =: f(t, y)$

$\text{dom}(f) = \mathbb{R}^* \times [0, +\infty[$   
 $f \in C^1$  nel dom: n.o  $\Rightarrow$  TEUL applicabile  
 $\forall (t_0, x_0) \in \mathbb{R}^* \times ]0, +\infty[$

$f(t, y) = \left( -\frac{2y}{t} \right) \left( 3 + t^3 y^{1/2} \right)$

$f(t, y) = 0 \Leftrightarrow$   
 $y = 0$  (sol. cost.)  
 due



oppure  $3 + t^3 y^{1/2} = 0$

$t > 0 : 3 + t^3 y^{1/2} > 0$

$t < 0 : 3 + t^3 y^{1/2} \geq 0 \Leftrightarrow t^3 y^{1/2} \geq -3$

$\Leftrightarrow y^{1/2} \leq -\frac{3}{t^3}$

$\Leftrightarrow y \leq \frac{9}{t^6}$

$y = \frac{9}{t^6}, t < 0$

zero-clina

Asintoti?

$y' = -\frac{6}{t} y - 2t^2 y^{3/2}$

Annotations:  $\alpha \in \mathbb{R}$  (under  $y$ ),  $+10$  (under  $t^2$ ),  $\alpha^{3/2}$  (under  $y^{3/2}$ ),  $0$  (under  $t$ )

$\Rightarrow \alpha = 0$  unico possibile valore per as. orizzontale

$\alpha \neq 0 : y'$  diverge !!

$y^{-3/2} y' = -\frac{6}{t} y^{-1/2} - 2t^2$

$z = y^{-1/2}$

$z > 0$

$z' = -\frac{1}{2} y^{-3/2} y'$

$-\frac{1}{2} y^{-3/2} y' = \frac{3}{t} y^{-1/2} + t^2$

$z' = \frac{3}{t} z + t^2$

$z(t) = e^{3 \ln|t|} \int e^{-3 \ln|t|} t^2 dt$

$= |t|^3 \int \frac{1}{|t|^3} t^2 dt$

$|t|^3 = t^3 \cdot (\text{sign}(t))^3$

$= t^3 \text{sign}(t)$

$= |t|^3 \int \frac{\text{sign}(t)}{t^3} t^2 dt$

$= |t|^3 \text{sign}(t) \int \frac{1}{t^3} t^2 dt = t^3 \int \frac{1}{t} dt$

$$= t^3 (\ln|t| + c) \quad c \in \mathbb{R}$$

Condizione :  $z_c(t) > 0$

$$\ln|t| + c > 0 \Leftrightarrow \ln|t| > -c \Leftrightarrow |t| > e^{-c}$$

	$-e^c$	$0$	$e^{-c}$
$t^3$	-	-	+
$\ln t  + c$	+	-	+
$z_c(t)$	-	$\oplus$	$\oplus$

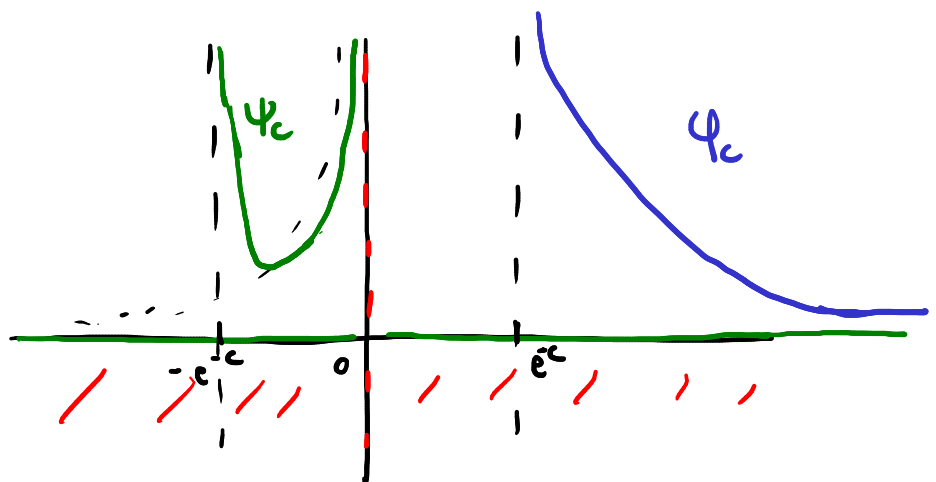
$$z = y^{-\frac{1}{2}} \quad y = z^{-2}$$

$\forall c \in \mathbb{R}$ : due soluzioni:

$$\bullet \psi_c(t) = \frac{1}{(z_c(t))^2} = \frac{1}{t^6 (\ln|t| + c)^2} \quad t \in ]e^c, +\infty[$$

$$\bullet \psi_c(t) = \frac{1}{(z_c(t))^2} \quad t \in ]-e^{-c}, 0[$$

$$\psi_c(t) \xrightarrow[t \rightarrow 0^-]{} +\infty$$



$$j \in \{1, \dots, n-1\}, \quad f_j(t, x_1, \dots, x_n) = x_{j+1}$$

$$|f_j(t, \underbrace{x_1, \dots, x_n}_x) - f_j(t, \underbrace{y_1, \dots, y_n}_y)| = |x_{j+1} - y_{j+1}|$$

$$\leq \|x - y\|$$

$$= 1 \cdot \|x - y\|$$

$\Rightarrow f_j$  è lipschitziana con  $L = 1$

$f: I \times \mathbb{R}^n \rightarrow \mathbb{R}$  è **sublineare** se  $\forall k \subset I$  compatto

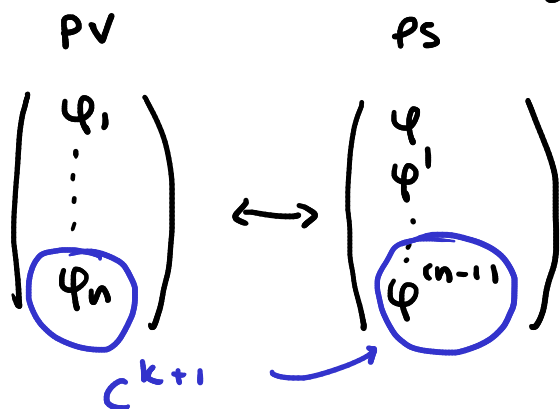
esistono  $p, q_1, \dots, q_n \in \mathbb{R}_+$  t.c.  $\forall (t, x_1, \dots, x_n) \in k \times \mathbb{R}^n$

$$|f(t, x_1, \dots, x_n)| \leq p + q_1|x_1| + q_2|x_2| + \dots + q_n|x_n|$$

Oss:  $f$  è sublineare  $\Leftrightarrow$  lo sono tutte le sue componenti

$$(\|f\| \leq |f_1| + \dots + |f_n|)$$

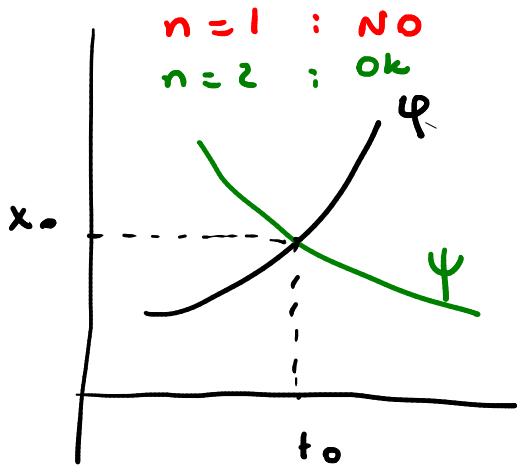
$f \in C^k \Rightarrow f \in C^k \Rightarrow$  le sol. d: (PV) sono di classe  $C^{k+1}$



$$\varphi^{(n-1)} \in C^{k+1} \Rightarrow \varphi^{(n-2)} \in C^{k+2} \Rightarrow \varphi^{(n-3)} \in C^{k+3}$$

$$\dots \Rightarrow \varphi^{(n-n)} \in C^{k+n}$$

$$\varphi^{(0)} = \varphi$$



$$\begin{cases} \varphi'' = f(t, \varphi, \varphi') \\ \varphi(t_0) = x_0 \\ \varphi'(t_0) = x_1 \end{cases}$$

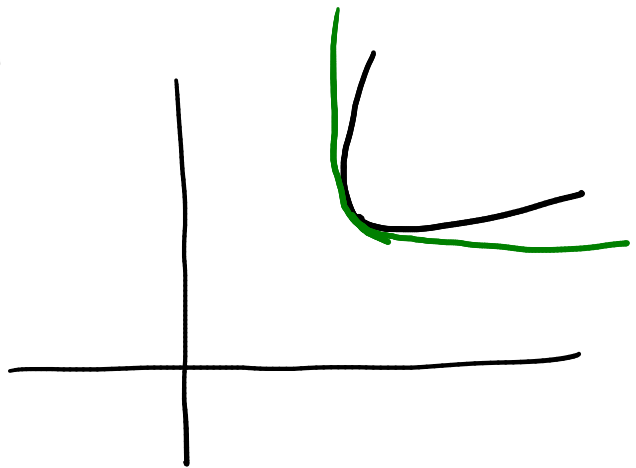
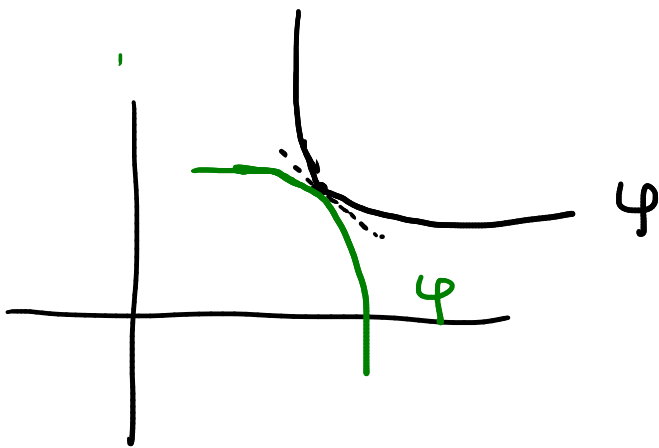
$$\varphi(t_0) = x_0 \quad \varphi(t_0)$$

$$\varphi'(t_0) > 0$$

$$\varphi'(t_0) < 0$$

$$\neq$$

$n=2$  : NO!



$$y^{(n)} + a_{n-1} \ln y^{(n-1)} + \dots + a_1 \ln y' + a_0 \ln y = b \ln$$

$$y^{(n)} = b \ln - a_0 \ln y - a_1 \ln y' - \dots - a_{n-1} \ln y^{(n-1)}$$

$$f(t, x_1, \dots, x_n) := b \ln - a_0 \ln x_1 - a_1 \ln x_2 - \dots - a_{n-1} \ln x_n$$

Suppongo  $a_0, a_1, \dots, a_{n-1}, b \in C(I, \mathbb{R})$

•  $\text{dom}(f) = \underline{I \times \mathbb{R}^n}$

•  $a_0, \dots, a_{n-1}, b$  continui  $\Rightarrow$   $f$  continua ( $= C^0$ )  
( $\stackrel{\text{regol.}}{\Rightarrow}$  soluz. di classe  $C^n$ )

•  $\forall j \in \{1, \dots, n\}$ :

$$\frac{\partial f}{\partial x_j}(t, x_1, \dots, x_n) = \underline{a_{j-1}(t)}$$

continua in  $I$  (funz. della var.  $t$ )

$\Rightarrow$  continua in  $I \times \mathbb{R}^n$  (funz. di  $(t, x_1, \dots, x_n)$ )

cond. suff.

$\Rightarrow$   $f$  è loc. lipsc. rispetto a  $x$  unif. in  $t$

•  $\forall (t, x_1, \dots, x_n) \in I \times \mathbb{R}^n$ :

$$|f(t, x_1, \dots, x_n)| = |b(t) - a_0(t)x_1 - \dots - a_{n-1}(t)x_n|$$

$$\leq |b(t)| + |a_0(t)||x_1| + \dots + |a_{n-1}(t)||x_n|$$

Fisso  $K \subseteq I$  compatto

$\forall (t, x_1, \dots, x_n) \in K \times \mathbb{R}^n$ :

$$|f(t, x_1, \dots, x_n)| \leq \underbrace{\max_{t \in K} |b(t)|}_{=: p} + \underbrace{\max_{t \in K} |a_0(t)|}_{=: q_1} |x_1| + \dots + \underbrace{\max_{t \in K} |a_{n-1}(t)|}_{=: q_n} |x_n|$$

$\leftarrow$   $\uparrow$   $\rightarrow$   
esistono per teor. Weierstrass

$\Rightarrow$   $f$  è sublineare



Quanto segue riguarda il "seminario" sui sistemi differenziali lineari. E' stato improvvisato in aula; appena possibile lo inserirò nelle "slide".

$$y' = A(t)y + B(t)$$

Se  $(\varphi_1, \dots, \varphi_n)$  sol. di  $y' = A(t)y$

Int. gen. di omog.:

$$c_1 \varphi_1 + \dots + c_n \varphi_n \quad c_1, \dots, c_n \in \mathbb{R}$$

$$= \begin{pmatrix} \varphi_1 & \dots & \varphi_n \end{pmatrix} \begin{pmatrix} c_1 \\ \vdots \\ c_n \end{pmatrix} = W(t)C \quad C = \begin{pmatrix} c_1 \\ \vdots \\ c_n \end{pmatrix} \in \mathbb{R}^n$$

Cerco  $\bar{\varphi}(t) = W(t)C(t) \quad C = C(t) \quad \text{funz. vettoriale}$

$$\bar{\varphi}'(t) = W'(t)C(t) + W(t)C'(t)$$

$$\begin{pmatrix} \varphi_{11} c_1 + \varphi_{21} c_2 + \dots + \varphi_{n1} c_n \\ \vdots \\ \vdots \\ \vdots \end{pmatrix} = W(t)C(t)$$

$$\begin{pmatrix} \varphi'_{11} c_1 + \varphi_{11} c'_1 + \varphi'_{21} c_2 + \varphi_{21} c'_2 + \dots + \varphi'_{n1} c_n + \varphi_{n1} c'_n \\ \vdots \\ \vdots \end{pmatrix}$$

$$\begin{pmatrix} \varphi'_{11} c_1 + \varphi'_{21} c_2 + \dots + \varphi'_{n1} c_n \\ \vdots \\ \vdots \end{pmatrix} + \begin{pmatrix} \varphi_{11} c'_1 + \varphi_{21} c'_2 + \dots + \varphi_{n1} c'_n \\ \vdots \\ \vdots \end{pmatrix}$$

$$W'(t) C(t) + W(t) C'(t)$$

$$\underbrace{W'(t) C(t)}_{\bar{\varphi}'(t)} + \underbrace{W(t) C'(t)}_{A(t) \bar{\varphi}(t)} = A(t) W(t) C(t) + B(t)$$

$$W'(t) = A(t) W(t) \quad \text{eq. matrix.}$$

$$\varphi' = A(t) \varphi \quad \text{eq. vec.}$$

$\bar{\varphi}$  r.s. eq. completa  $(=)$

$$\underbrace{W(t) C'(t)}_{\text{invertible}} = B(t) \quad (=)$$

$$C'(t) = W(t)^{-1} B(t)$$

$$C(t) = \int W(t)^{-1} B(t) dt \quad \dots$$